

ΠΑΡΑΡΤΗΜΑ

ΣΥΝΟΠΤΙΚΟΣ ΟΔΗΓΟΣ ΤΟΥ COMPREHENSIVE CONTROL

Commands: Names and descriptions

Prompts:

CC> Laplace transfer functions (ANALOG mode)
DIG> z-transfer functions (DIGITAL mode)
STATE> real matrices and state space quadruples
DATA> real and complex data files
MACRO> macro text editor

Data Entry:

ENTER Front end for
all data entry commands
GENTER [,Name,coeffs] Transfer
function
SENER [,Name,coeffs] Transfer
function, shorthand notation
ZENTER [,Name,coeffs,{delay}] Transfer
function, z^{-1} notation
FENTER [prompts only] Function of
transfer functions
HENTER [,Name,#rows,#cols] Transfer
function matrix, elements prompted
PENNER [,Name,#rows,#cols,#states,coeffs]
Quadruple, elements row-wise
CENTER [,Name,#rows,#cols,coeffs] Complex matrix,
elements real,imag row-wise
DENTER [,Name,#rows,#cols,type] Data file, real
or complex
INPUT [,Name,#rows] Time series
(real data file)

Data Inquiry:

WHAT [,Name] Determines data
type of Name

Data Display:

DISPLAY [,Name] Display any data

type		
PZF	[,Name]	Display tf in
pole-zero-form		
TCF	[,Name]	Display tf in
time constant form		
SHORTHAND	[,Name]	Short hand form,
complex=	[zeta,mag]	
SINGLE	[,Name]	Display tf as
ratio of single polys		
UNITARY	[,Name]	Display all
polynomials as unitary		
PFE	[,Name]	Partial fraction
expansion		
ILT	[,Name{,CAUSAL/,ANTI/,roc}]	Inverse
Laplace transform		
IZT	[,Name{,CAUSAL/,ANTI/,roc}]	Inverse
z transform		
ZDISPLAY	[,Name]	Transfer function
in z ⁻¹ notation		
ZPZF	[,Name]	PZF in z ⁻¹
notation		
LPDISPLAY	[,Name{,'message'}]	Line printer
display of any data type		
LPPZF	[,Name{,'message'}]	Line printer PZF
display		
LPSHORTHAND	[,Name{,'message'}]	Line printer
SHORTHAND display		
LPZDISPLAY	[,Name{,'message'}]	LPDISPLAY in z ⁻¹
notation		
LPZPZF	[,Name{,'message'}]	LPPZF in z ⁻¹
notation		
SCAN	[,Name]	Scan data file
index		
FORMAT	[precision,zeros]	Set format for
displays		

Data changing:

CHANGE	[,Name1,Name2]	Front end to other
change commands		
GCHANGE	[,Name1,Name2]	Change coeffs of

transfer function		
FCHANGE	[,Name1,Name2]	Change function of
tf's		
PCHANGE	[,Name1,Name2]	Change coeffs of
state space quadruple		
DELAY	[,time]	Multiply all tf's by
exp(-sT) delay		
COPY	[,Name1,Name2]	Copy Quadruple to
and from Data file		
CHPZF	[,G1,G2]	G2=Pole-Zero-Form of
G1		
CHTCF	[,G1,G2]	G2=Time-Constant-
Form of G1		
CHUNITARY	[,G1,G2]	G2=Unitary
polynomial form of G1		
CHSINGLE	[,G1,G2]	G2=Single polynomial
form of G1		
CHGCD	[,G1,G2]	G2=tfm G1 with
G1_c=Greatest Common Divisor		
CHLCM	[,G1,G2]	G2=tfm G1 with
G1_c=Least Common Multiple		
CHPOLY	[,G1,G2]	G2=tfm G1 with
polynomial elements		
CHONE	[,G1,G2]	G2=tfm G1 with
G1_c=1		
EXTRACT	[,G1,G2, i,j/ALL]	G2=tf extracted from
tfm G1		

Equation interpreters symbolically enter, display and change data elements:

CC> real matrices, transfer functions,
transfer functions matrices

STATE> real matrices, state space quadruples,
transfer functions (input only)

DATA> real matrices, complex matrices, real and
complex data files

Reduced order transfer functions:

NEAR [,G1,G2{,option,eps}] Cancel
poles/zeros with eps tolerance

LFAPPROX [,G1,G2,omega,order] Low freq
approximation
HFAPPROX [,G1,G2,omega,order] High freq
approximation

DOS file transfer:

STORE [,Name,DOS filename] Store Name in
DOS filename
RECALL [,DOS filename,Name] Recall Name from
DOS filename

MACRO Execution:

Syntax: @<name>,&1,&2,... (up to 40 parameters)
Macros can be called from CC, STATE, or DATA
command levels
Execution always begins in CC level, even if
called from STATE or DATA.

Interactive graphics and spreadsheet:

PLOT [,Name,axis,AUTO] Plot of real or complex
data file
STRIP CHART [,Name,AUTO] Strip chart of real
vector data file
SPREAD SHEET [,Name] Matrix spreadsheet

HP plotter support

! plot option from PLOT commands drives plotter or
creates file
HPINIT Initialize HP plotter communication
(otherwise use defaults)
HPLOT [,File] Plot from previously created .HP
file

Flow control, nesting okay:

FOR x=matrix & statements & END
WHILE expression & statements & END
IF expression & ELSEIF expression & ELSE
statements & END

Screen control:

back=0-31, pallete=0-1,
 face=0-3, hands=0-3
 CALCULATOR HP-like Reverse Polish
 calculator
 TIC-TAC-TOE Nonsense, beat the
 computer!
 KILL [,DOS file] Kill DOS file (use
 wildcards, defaults to data dir.)
 SETUP Setup operating environment, only from CC
 level:
 Screen parameters
 Location of CC modules (e.g. for RAM disk)
 History file continuation
 Establish links to user defined commands

Classical control plots, parameters shown for AUTO scaling:

FREQUENCY [,G,low,high,#pts,type] Create FREQ =
 data file for tf's
 DFREQUENCY [,G,low,#pts,#reps,type] Create FREQ
 using foldover pi/T
 POINT [G,omega] Name at
 $s=j*\omega$ or $z=e^{(j*\omega*T)}$
 MARGIN [,G{,omega}] Robustness
 margins, default omega=1 r/s
 LPMARGIN [,G{,omega}] Line printer
 display of MARGIN
 BODE [,type,AUTO] Bode plot using
 FREQ data file
 NYQUIST [,AUTO] Nyquist plot
 using FREQ data file
 INVERSE NYQUIST [,AUTO] Inverse Nyquist
 plot using FREQ data file
 LOG NYQUIST [,AUTO] Nyquist is log
 axes using FREQ data file
 NICHOLS [,AUTO] Nichols chart
 using FREQ data file
 TIME [,G,option,AUTO] Time response
 using inverse Laplace of G(s)
 DTIME [,G,option,AUTO] Time response

using inverse z of $G(z)$

SIMULATION	[,G,T,opt,AUTO]	Dig. sim. using bilinear of $G(s)$
DSIMULATION	[,G,option,AUTO]	Dig. sim. using $G(z)$
ROOT LOCUS	[,G,INFO/,AUTO]	Root locus, gain step algorithm
FASTRL	[,G,INFO/,AUTO]	Root locus, curve tracing algorithm
SIGGY	[,G,option,AUTO]	Siggy and Bode root locus
ASYMPTOTE	[,G,type,AUTO]	Same as SIGGY

Transfer function filters:

1POLE	[,G,a]	Single pole
2POLES	[,G,zeta,wn]	Two poles
1ZERO	[,G,a]	Single zero
2ZEROS	[,G,zeta,wn]	Two zeros
LEADLAG	[,G,freq,phase]	Leadlag, -90 to 90 phase at freq
NOTCH	[,G,wn,zetan,zetad]	Notch at wn, depth = zetan/zetad
INTEGRATOR	[,G]	Integrator
BUTTERWORTH	[,G,freq,order]	Butterworth
BESSEL	[,G,freq,order]	Bessel
CHEBYSHEV	[,G,freq,dB,order]	Chebyshev, 0-3dB passband ripple
ITAE	[,G,freq,order]	ITAE lowpass filter
PADEDELAY	[,G,time,order]	Pade approx of $\exp(-s*time)$

Transfer function sampled-data and multi-rate commands:

CONVERT	[,G1,G2,option,time]	Convert $G1(s)$ to $G2(z)$, 10 options
WPLANE	[G1,G2]	Convert $G1(z)$ to $G1(w)$
SKIP	[,G1,G2,n]	Skip sampling algorithm, every nth sample

EXPAND	[,G1,G2,n]	Samples spaced n
apart with zero fill		
REPLACE	[,G1,G2,n]	z^{n*i} replaced with
z^i		

Mix Laplace and z-transforms using functions of transfer functions.
 Create these functions using the FENTER, FCHANGE, and FDISPLAY commands.
 Perform frequency analysis using FREQUENCY, DFREQUENCY, BODE, NYQUIST, and NICHOLS.

Miscellaneous analysis:

STABILITY	[,G]	Tf unity feedback c.l. stability.
ROUTH	[,G]	Tf range of stable gains
MEAN SQUARE	[,G{,Y}]	Error, set Y=error if Y present

TF Wiener-Hopf, IMC, Hinf & Diophantine commands:

INNER	[,G,Gin{,div}]	Inner factor, div=stable/unstable boundary
OUTER	[,G,Gout{,div}]	Outer factor
BLASHKY	[,G,B{,div}]	Blashky product
ADJOINT	[,G,Gstar{,div}]	Adjoint
SPECTRAL	[,option,G,G1,G2{,div}]	Spectral factorization
PARTIAL	[,option,G,G1,G2{,div}]	Partial factorization
WIENER	[,a,b,c{,div}]	Wiener-Hopf minimization
WHOF	[,a,b,c,d{,div}]	Wiener-Hopf Optimal Filter
WHLQR	[,G,Glqr{,rho,div}]	Wiener-Hopf Linear Quadratic Regulator
WHLQG	[,G,Gd,K{,mu,div,delay}]	Wiener-Hopf Linear Quadratic Gaussian
HINFINITY	[,a,b{,c}{,h}{,gamma}]	H-infinity minimization
DIOPHANTINE	[G,Phi,K]	Diophantine

equation
 DIOPOLE [,G,K] Diophantine eq.
 pole-placement
 DIOLQG [,G,Gd,K{,mu}] Diophantine eq.
 LQG

**STATE command level uses state space quadruples,
 packed A,B,C,D matrices**

$$\begin{array}{l}
 P = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \quad dx/dt = A*x + B*u \quad H(s) = \\
 C*(sI-A)^{-1}*B + D \\
 \quad \quad \quad \quad \quad \quad y = C*x + D*u
 \end{array}$$

Poles and zeros:

POLES [,P] Poles of P =
 eigenvalues of P(A)
 ZEROS [,P{,thresh}] Multivariable zeros
 of P, by QZ algorithm
 CONMATRIX [,Pi,P] Create P =
 controllability matrix for system Pi
 OBSMATRIX [,Pi,Q] Create Q =
 observability matrix for system Pi
 CONTROLLABILITY [,P,radius] Determine cont. and
 obs.
 OBSERVABILITY [,P,radius] Determine cont. and
 obs.
 POLE PLACEMENT [option,Pi,Pj] SISO pole placement

Transformations:

CCF [,G,P] P = controllable
 canonical form of G
 OCF [,G,P] P = observable
 canonical form of G
 DCF [,G,P] P = diagonal
 canonical form of G
 FADEEVA [,P,H] H = P by Fadeeva's
 method (H is a tf or tf matrix)
 GEP [,P,H{,thresh}] H = P by QZ algorithm
 (H is a tf or tf matrix)
 NUMERATOR [prompts only] Coupling numerators

of quadruple by QZ algorithm
 BALANCE [,Pi,Pj{,INFO}] Pj = balanced Pi,
 INFO to print diag scaling
 SIMILARITY [,1,Pi,T,Pj] Pj = simil. trans. of
 Pi using T
 or [option,Pi,Pj,order] options 2,3,4 use
 T=Hess./Schur/Eig-vectors of Pi
 RESIDUALIZATION [,Pi,Pj,n] Pj = residualized Pi,
 keep n states
 SUBSYSTEM [option,Pi,Pj] Pj = subsystem of Pi
 (stable, contr, obs, etc)
 BALREAL [,Pi{,In,Out},Pj] Pj = balanced
 realization of Pi; In,Out=weights
 SBALANCE [,Pi{,Pj,In},Out,k] Pj = Schur balanced
 model reduction

Matrix decompositions:

HESSENBERG [,A,H,U] Hessenberg
 comp: $A=U*H*U'$
 SCHUR [,A,T,U,order] Schur comp:
 $A=U*T*U'$
 EIGENVALUE [,A,D,X,order] Eigenvalue
 comp: $A=X*diag(D)*X^{-1}$
 GHESSENBERG [,A,B,H,T,Z] Gen. Hess.
 comp: $A=Q*H*Z, B=Q*T*Z$
 GSCHUR [,A,B,Tb,T,Z,order] Gen. Schur
 comp: $A=Q*Tb*Z, B=Q*T*Z$
 GEIGENVALUE [,A,B,D,X,order] Gen. eig. comp:
 $A*X=B*X*diag(D)$

Singular value decomposition (SVD) and applications:

SVD [,A,S,U,V] SVD:
 $A=U*diag(S)*V'$
 PSEUDO INVERSE [,A,Aplus,eps] Aplus =
 $V*S^+*U'$
 SUBSPACE [option,A,B,eps] B = Range or
 Null space of A or A'
 PROJECTION [option,A,B,eps] B = projection
 onto subspace of A

NORM	[A] or [option,A,B]	6 norms of A
RANK	[A, {B}, eps]	Rank of A
CONDITION	[A, {B}, eps]	Condition

number of A

Matrix equations:

LYAPUNOV	[, F, G, P]	$F'P + PF + G = 0$
SYLVESTOR	[, F, G, H, P]	$FP + PG + H = 0$
RICCATI	[, F, G, H, P]	$F'P + PF + G - PHP = 0$
DLYAPUNOV	[, F, G, P]	$F'PF - P + G = 0$
DRICCATI	[, F, G1, G2, H, P]	$F'PF - P + H - F'PG1(G2 - G1'PG1)^{-1}G1'PF = 0$

Optimal control:

LQR	[as prompted]	Linear quadratic regulator
KBF	[as prompted]	Kalman Bucy filter
LQG	[as prompted]	Linear quadratic Gaussian problem
DLQR	[as prompted]	Digital Linear quadratic regulator
DKBF	[as prompted]	Digital Kalman Bucy filter
DLQG	[as prompted]	Digital Linear quadratic Gaussian problem

Optimal control using connection matrix:

H2	[M, #inputs, #outputs, K, {X}, {Y}{, comp}]	H2 minimization
HINFINITY	[M, #inputs, #outputs, K, {Xinf}, {Yinf}{, comp}]	Hinf minimization

Sampled-data and multi-rate analysis:

CONVERT	[Pi, Pj, option, T]	Pj = discretized Pi, 11 options
WPLANE	[Pi, Pj]	Pj = W-plane version of digital Pi
SKIP	[, Pi, Pj, n]	Pj = skip sampled Pi
EXPAND	[, Pi, Pj, n]	Pj = expanded Pi
EXPONENTIAL	[, Pi, Pj, T{, n}]	Pj = discretized

Pi using matrix exponential

WPRIME	[Pi,Pj]	Pj = W-plane
version of analog Pi		
ADVANCE	[,Pi,Pj]	Pj = z*Pi
DELAY	[,Pi,Pj]	Pj = Pi/z
RIPPLE	[,P,r,n]	P = [I I/z ...
I/z^(n-1)], r x r*n		
CONNECT	[,P,r,m,nhat]	P = connection
matrix		
VECTORIZE	[,Name1,Name2,n]	Name2 = input
vectorized Name1		
REDUCE	[,Name1,Name2,n]	Name2 = output
reduced Name1		
KRANC	[,Pi,Pj,option,T,m,n]	Pj = Kranc
operator of Pi		

State space filters:

1POLE	[,P,a]	Single pole
2POLES	[,P,wn,zeta]	Two poles
LEADLAG	[,Pi,freq,phase]	Leadlag, -
90 to 90 phase at freq		
NOTCH	[,P,wn,zetan,zetad]	Notch at
wn, depth = zetan/zetad		
INTEGRATOR	[,P]	Integrator
BUTTERWORTH	[,P,freq,order]	Butterworth
BESSEL	[,P,freq,order]	Bessel
CHEBYSHEV	[,P,freq,dB ripple,order]	Chebyshev,
0-3dB passband ripple		
ITAE	[,Pi,freq,ordr]	ITAE
lowpass filter		
PADEDELAY	[,P,time,order]	Pade approx
of exp(-s*time)		

Miscellaneous:

FEEDBACK	[,option,P1,P2,P3,n]	Pj or Pk =
Pi or Pi,Pj with feedback		
PACK	[,A,B,C,D,P]	P = (A,B;C,D)
UNPACK	[,P,A,B,C,D]	(A,B;C,D) = P
MEAN SQUARE	[,P{,Y}]	Error, set
Y=error if Y present		

GRAMMIAN [,option,P,Y] Control-
and observ-ability Grammians

Data files are indexed real or complex matrices:

Header
<index>

Matrix ordered row-wise
<index>

Matrix ordered row-wise

Usually, but not necessarily, data files contain
time or frequency data

High level functions [Available only in DATA level]:

EIGENVALUE [,Name1,Name2] Name2 = eigenvalues
of Name1

SVD [,Name1,Name2] Name2 = singular
values of Name1

FMU [,Name1,Name2{,structure}] Name2 = structured
s.v.'s of Name1

RMU [,Name1,Name2{,structure}] Name2 = real param.
structured s.v.'s of Name1

Equations

CC equation interpreter: <LHS>=<RHS>

Allowable data types: tf's, tf matrices, real
matrices

Rules for <LHS> (left hand side):

If <LHS> is missing then display <RHS>

<LHS>=Name, store <RHS> at Name

<LHS>=Name(N/D{,poly{,coeff}}), change numer,
denom, polynomial, and/or coeff.

<LHS>=Name(row,col), change tf or real matrix
element, augment with matrix

Rules for <RHS> (right hand side):

Operators and precedence: () : ! ' ^ |
*/\ +- , ; #

Feedback operation: a|b = a/(i+b*a)

Real or tf matrix building: , ; # = row, col,
diagonal augmentation

scalar + square matrix = scalar*identity + square matrix

Colon convention: i:j:k = row vector containing i to k step j, default j=1

Special numbers: pi=3.14..., rnd=random number, i=1

Rules for selecting parts of data elements:

Name(rows,cols)= selected rows and cols of real or tf matrix

where 'rows' and 'cols' are row vectors, e.g. 1 1:4 1:2:7 (1,2,5)

Name(C) = tf which multiplies each element of a tf matrix

Name(N/D) = numerator or denominator of transfer function

Name(N/D,i) = i'th polynomial counting left to right as displayed

Name(N/D,i,j) = s^j'th coefficient of i'th polynomial

Functions used in CC equation interpreter:

DET(Name) = determinant

TRACE(Name) = trace

DER(Name) = derivative

EPS(Name,eps) = set elements or coefficients < eps to zero

NORM(Name) = Frobinius norm (sqr of sum of squares) of real matrix

ZERO(r,m) = r x m matrix of zeros

ONES(r,m) = r x m matrix of ones

RND(r,m) = r x m matrix of random numbers

IDEN(r) = r x r identity matrix

RDIM(Name) = row dimension

CDIM(Name) = column dimension

ODIM(Name) = output dimension, same as row dimension

IDIM(Name) = input dimension, same as column dimension

NUM(A,B,outputs,input) = coupling numerator, A,B = tf (usually poly) matrices

Matrix element functions:

LOG	SIN	ASIN	SINH	INT
SQR				
LOG10	COS	ACOS	COSH	SGN
EXP	TAN	ATN	TANH	ABS

STATE equation interpreter: <LHS>=<RHS>

Allowable data types: real matrices, quadruples, tf's (input only)

Rules for <LHS> (left hand side):

If <LHS> is missing then display <RHS>

<LHS>=Name, store <RHS> at Name

<LHS>=Name({A/B/C/D},row,col), change element, augment with matrix or quad

row=0 implies (max row)+1, col=0 implies (max col)+1, for block augments

Rules for <RHS> (right hand side):

Operators and precedence: () : ! ' ^ |
*/\ +- , ; #

Feedback operation with minimal realization: $a|b = a/(i+b*a)$

Matrix/quadruple building: , ; # = row, col, diagonal augmentation

scalar + square matrix = scalar*identity + square matrix

Colon convention: i:j:k = row vector containing i to k step j, default j=1

Special numbers: pi=3.14..., rnd=random number, i=1

If Name=tf then convert to quadruple using CCF realization

Dot operations (element by element): .^ .*
./ .\ .+ .-

Relations: == > >= < <= <>

Logic: @and @or not()

Rules for selecting parts of a quadruple:

Name({A/B/C/D},rows,cols) = selected A,B,C,D;
rows, and cols

Name(S,states) = selected states

Functions used in STATE equation interpreter:

DET(Name) = determinant
TRACE(Name) = trace
EPS(Name,eps) = set elements of Name < eps to zero
NORM(Name) = Frobinius norm (sqr of sum of squares) of Name
ZERO(r,m) = create r x m matrix of all zeros
ONES(r,m) = create r x m matrix of all ones
RND(r,m) = create r x m random matrix
IDEN(r) = create r x r identity matrix
DIAG(Name) = change matrix with 1 or 2 rows (or cols) to diag. matrix
CHST(Name,n) = change # states of Name to n
ADJ(Name) = Adjoint of Name, (-A',C';-B',D')

SCALE(Name,alpha) = Scaled Name, (1/alpha*A,1/alpha*B;C,D)
EXIST(name) = true(1) if datafile name exists, else false(0)

Matrix/Quadruple dimensions:

SDIM(P) = # states
RDIM(P) = ODIM(P) = # rows (equivalently # outputs)
CDIM(P) = IDIM(P) = # columns (equivalently # inputs)

Matrix element functions

LOG	SIN	ASIN	SINH	INT
SQR				
LOG10	COS	ACOS	COSH	SGN
EXP	TAN	ATN	TANH	ABS

DATA equation interpreter: <LHS>=<RHS>

Allowable data types: data files, real & complex matrices

Algebra is performed for data files at each matching index.

Indexes for binary operations must match within

relative distance of 10^{-5}

Options for <LHS> (left hand side):

If <LHS> is missing then display <RHS>

<LHS>=Name, store <RHS> at Name

<LHS>=Name(row,col), change element, augment with data file or matrix

Rules for <RHS> (right hand side):

Operators and precedence: () : ! ' ^ |
*/\ +- , ; #

Feedback operation: $a|b = a/(i+b*a)$, complex conjugate: a'

Matrix building: , ; # = row, col, diagonal augmentation

scalar + square matrix = scalar*identity + square matrix

Colon convention: $i:j:k$ = row vector containing i to k step j , default $j=1$

Special numbers: $\pi=3.14\dots$, rnd=random number, $i=1$, $j=\sqrt{-1}$

Enter complex number as real + $j*\text{imag}$

Rules for selecting parts of a data file or matrix:

Name = entire data file or matrix

Name(A/B/C/D) = part of quadruple (entire quadruple not allowed)

Name(rows,cols) = selected rows and cols of data file or matrix

where rows,cols = row vectors containing entries

Functions used in DATA equation interpreter:

DET(Name) = determinant

TRACE(Name) = trace

EPS(Name,eps) = set elements of Name < eps to zero

NORM(Name) = Frobinius norm (sqr of sum of squares) of Name

ZERO(r,m) = create $r \times m$ matrix of all zeros

ONES(r,m) = create $r \times m$ matrix of all ones

RND(r,m) = create $r \times m$ random matrix

IDEN(r) = create r x r identity matrix
 RDIM(Name) = row dimension
 CDIM(Name) = column dimension
 ODIM(Name) = output dimension, same as row dimension
 IDIM(Name) = input dimension, same as column dimension
 SKIP(Name,n) = select every n'th index
 MERGE(Name1,Name2) = merge indexes with preference for Name1
 INDEX(Name,low,high) = select indexes from low to high
 CHIN(Name,alpha,beta) = change index to $\alpha \cdot \text{index} + \beta$

Matrix element functions

LOG	SIN	ASIN	SINH	INT
SQR	CONJ			
LOG10	COS	ACOS	COSH	SGN
REAL	PHASE			
EXP	TAN	ATN	TANH	ABS
IMAG				